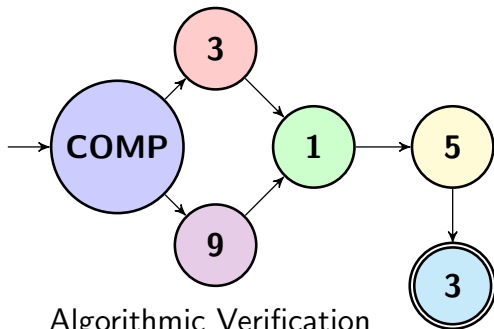




Timed CTL and TCTL_C

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Timed Logic

Timed CTL

TCTL is CTL with clock constraints (as in TA) attached to **U** (and derived operators).

Note: The next-state operator **X** has no meaning in dense time.

Syntax

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \mathbf{E} \varphi \mathbf{U}_{\sim c} \varphi \mid \mathbf{A} \varphi \mathbf{U}_{\sim c} \varphi$$

Where $p \in \mathcal{P}$ is an atomic proposition and $(\sim) \in \{<, \leq, =, \geq, >\}$.

TCTL Semantics

Semantics are defined on a *timed transition system*.

Timed Transition Systems

A TTS is a timed automaton with a labelling function L associating sets of atomic propositions to states (analogous to Kripke structures).

Our modelling relation is defined on a *configuration* (state). Let $\text{Exec}(s)$ be the set of executions from configuration s , and $\text{Dur}(\rho|_{\leq k})$ be the sum of delays along the prefix $\rho|_{\leq k}$ of the execution ρ .

$$s \models p \quad \Leftrightarrow \quad p \in L(s)$$

$$s \models \mathbf{A} \varphi \mathbf{U}_{\sim k} \psi \quad \Leftrightarrow \quad \forall \rho \in \text{Exec}(s). \rho \models \varphi \mathbf{U}_{\sim k} \psi$$

$$s \models \mathbf{E} \varphi \mathbf{U}_{\sim k} \psi \quad \Leftrightarrow \quad \exists \rho \in \text{Exec}(s). \rho \models \varphi \mathbf{U}_{\sim k} \psi$$

$$\rho \models \varphi \mathbf{U}_{\sim k} \psi \quad \Leftrightarrow \quad \exists i. \text{Dur}(\rho|_{\leq i}) \sim k \wedge \rho_i \models \psi \wedge \forall j < i. \rho_j \models \varphi$$

Derived Operators

- Standard **U** is just **U**_{≥0}.
- Path formulae **F**_{~k} and **G**_{~k} are similar to normal CTL:

$$\mathbf{F}_{\sim k} \varphi \equiv \text{True } \mathbf{U}_{\sim k} \varphi$$

$$\mathbf{G}_{\sim k} \varphi \equiv \neg \mathbf{F}_{\sim k} \neg \varphi$$

Definition

A timed automaton $\mathcal{A}$ satisfies a formula φ , written $\mathcal{A} \models \varphi$ iff its initial configuration $(q_0, \bar{0})$ satisfies φ i.e. $(q_0, \bar{0}) \models \varphi$.

Example

The alarm is activated at most 10 time units after a problem occurs.

$$\mathbf{AG}(\text{problem} \Rightarrow \mathbf{AF}_{\leq 10} \text{ alarm})$$

Converting to Automata

Let's try to construct a timed (Büchi) automaton that accepts all timed words that satisfy this property:

$$\mathbf{AG}(\text{problem} \Rightarrow \mathbf{AF}_{\leq 10} \text{ alarm})$$

How do we know where to introduce clocks?

TCTL_C

TCTL is CTL with explicit clock constraints and reset.

Syntax

$$\varphi ::= x \sim k \mid x.\varphi \mid p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \mathbf{E} \varphi \mathbf{U} \varphi \mid \mathbf{A} \varphi \mathbf{U} \varphi$$

Where $x \in X$ is a **clock variable** and $(\sim) \in \{<, \leq, =, \geq, >\}$.

$x.\varphi$ is a **clock reset**.

Example (Alarm)

How do we express:

$$\mathbf{AG}(\text{problem} \Rightarrow \mathbf{AF}_{\leq 10} \text{ alarm})$$

in TCTL_C?

Expressivity

Result

All TCTL formulae are expressive in TCTL by introducing a fresh clock for each constrained operator:

$$\mathbf{E} \varphi \mathbf{U}_{\sim k} \psi \quad \equiv \quad (x. \mathbf{E} \varphi \mathbf{U} (\psi \wedge x \sim k))$$

The converse direction does not hold (Bouyer et al. 2005):

$$x. \mathbf{EF}(\varphi \wedge x < 1 \wedge \mathbf{EG}(x < 1 \Rightarrow \neg \psi))$$

cannot be expressed in TCTL.

Model Checking

Same techniques as reachability:

- ❶ Convert timed system A to discrete systems A' via region automata.
- ❷ Convert TCTL_C formula φ to standard CTL formula φ' on region automata.
- ❸ $A \models \varphi \iff A' \models \varphi'$, so apply standard CTL model checking.
- ❹ Checking is still PSPACE complete.

UPPAAL

A mature model checking framework for timed transition systems.
B. Srivathsan has released a video lecture on using UPPAAL on several examples here:

https://www.youtube.com/watch?v=tUSxi_rSXwo